





06:00 AM MIAMI | 12:00 HAMBURG



GATERS – Gate Rudder System as a Retrofit for the Next Generation Propulsion and Steering of Ships

By

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What is A GATE RUDDER SYSTEM (GRS) ?

- Classical single-rudder behind the propeller arrangement is replaced by twin-rudder blades with asymmetric cross-sections which are positioned either side of the propeller
- The Gate Rudder System, therefore, takes advantage of additional thrust generated by the two rudder blades, in contrast to the additional resistance resulted by the conventional rudder
- Each rudder blade can be controlled individually to affect the direction of the propeller's slipstream (i.e. to vector) and hence to steer the vessel with increased manoeuvring and motion control capability.

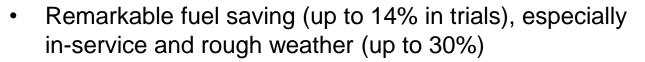




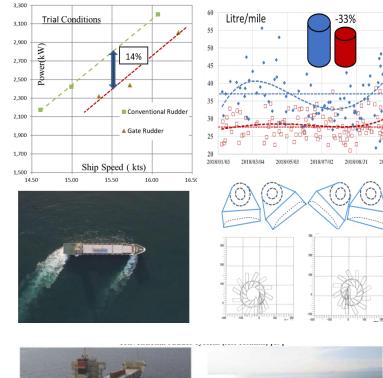


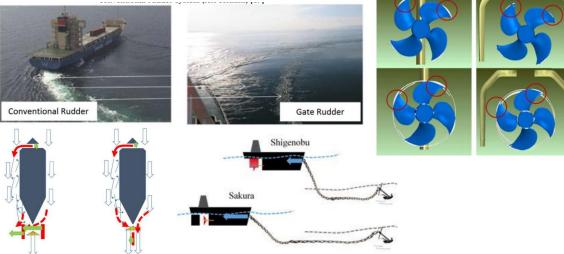


What are the advantages of A GATE RUDDER SYSTEM (GRS)?



- Reduced vessel motions (in yawing and rolling) in waves
- Improved steerability and manoeuvring (especially in harbours) without stern thrusters
- Reduced propeller loading and hence less vibration and URN
- Low wash wake due to hull waves & propeller slipstream
- Shorter ship length or more space at aft compared to the vessel with a conventional rudder behind the propeller
- Effective use of the bow thrusters at higher ship speeds
- Reduced risk of running anchor









A brief history of GATE RUDDER SYSTEM (GRS)



- GRS had its origin in "Frame Rudder" proposed and tested by <u>Mr Sadamoto Kuribayashi</u>of Kuribayashi Steam Co Ltd, Japan in 2011.
- Frame Rudder was tested and further improved by R&D conducted in NMRI of Japan by <u>Dr Noriyuki</u> Sasaki and this led to the 1st (Japanese) patent for the early version of GRS with a single rudder stock [# JP 2014-73815 A]
- Further R&D work in Japan and the UK at the Newcastle and Strathclyde Universities led by Dr Sasaki as the Visiting Professor resulted in the current shape of the GRS with two separate rudder stocks and the 2nd (European) Patent [# EP 3103715 A1]
- GRS was first applied on a 400TEU Japanese Container vessel "**Shigenobu**" through the R&D project sponsored by Nippon Foundation and a Japanese Consortium in 2017. The comparison of performance with her sister ship "**Sakura**" was well above the predictions.





First GRS application in Japan



- First application of the GRS was on a new build 400TEU Container vessel SHIGENOBU in 2017
- SHIGENOBU is the sister ship of SAKURA with the same size and engine power but with conventional (flap) rudder built in 2016
- As part of an R&D programme sponsored by Nippon Foundation and the Japanese Consortium the performance of both vessels were compared in speed trials in 2017 and later on through continuous performance monitoring in-service

SHIGEN	OBU			
Length overall	Loa	(m)	111.40	
Length between perpendiculars	L _{BP}	(m)		
Breadth	В	(m)	17.80	
Draught (midship)	Т	(m)	5.24	
Displacement	Δ	(ton)		
Service Speed	Vs	knots	15.5	
Rudder			GR	-O Br Mari





SAKURA	1			
Length overall	L _{OA}	(m)	111.4	
Length between perpendiculars	L _{BP}	(m)		
Breadth	В	(m)	17.8	
Draught (midship)	Т	(m)	5.24	
Displacement	Δ	(ton)		Imoto Lines
Service Speed	V_{S}	knots	15.5	
Rudder			CR	O konco oshita AlarineTraffic.com





So far, GRS APPLICATIONS



	SHIGENOBU (1 st Application, 2017)	KOHSIN MARU (2 nd Application, 2020)	SHINMON MARU (3 rd Application, 2020)
Type of ship	Container (400 TEU)	General cargo (509 GT)	General Cargo (499 GT)
Lpp	101.9	69	72
В	17.8	12	12
т	5.24	4.11	4.13
C _B	0.67	0.70	0.70
Design Vs	14.5	13	13
Fn (Lpp)	0.2436	0.267	0.267
L/B	5.72	5.75	5.75
Stern shape	V shape	Stern bulb	V shape















- A Japanese Consortium (JC) involving Kay Seven Co., Ltd., (Kuribayashi Steam Co Ltd); Mr. Noriyuki Sasaki, National Institute of Maritime, Port and Aviation Technology, Yamanaka Shipbuilding Co., Ltd. and Kamome Propeller Co., Ltd owns the Gate Rudder Patent (European Patent: EP 3103715)
- Further R&D and promotion activities in the University of Strathclyde (Glasgow) and Visiting Prof Noriyuki Sasaki attracted Wartsila Propulsion to purchase the commercial license from the JC to use the Gate Rudder technology protected by the Licensed Patent in 2020
- GATERS Project funding was granted by the EC (H2020) in December 2019 and the GATERS Consortium signed sub-license agreement with Wartsila Netherlands BV in 2021 on behalf of the Patent Holders hence:

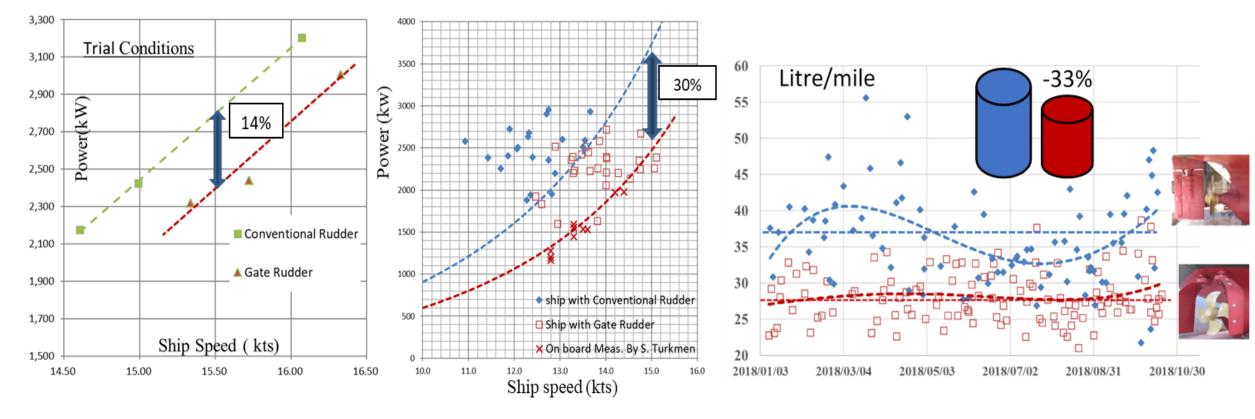
"GATERS has an official sub-licence agreement with Wartsila Netherlands BV to utilise the Gate Rudder Patent (EP 3103715) at specific retrofit projects of vessels sizes below 15,000. DWT. GATERS is sponsored by the EC H2020 Programme (ID: 860337) with the aims and objectives independent of Wartsila Netherlands BV"

	(19) Europäicher		
	All	(11) EP 3 103 715 A1	
	(12) EUROPEAN PATI published in accordan	ENT APPLICATION ce with Art. 153(4) EPC	
	(43) Date of publication: 14.12.2016 Bulletin 2016/50	(51) Int CL: B63H 25/38 ^(2006,01) B63H 25/30 ^(2006,01)	
	(21) Application number: 14881168.0(22) Date of filing: 19.11.2014	(86) International application number: PCT/JP2014/080623	
	(a.c.) Date of ming. 10.11.2014	 (87) International publication number: WO 2015/114916 (06.08.2015 Gazette 2015/31) 	
	 (84) Designated Contending States: A. A TE BO CH CY C2 DE DN EE ES FI FR OB GR IR HU IE IST LILI LUL VM CMK MT NL NO PL FT RO AS ES I SK SM KT Designated Extension States: B.M EE (30) Priority: 31.01.2014 JP 2014052040 (71) Applicates: KAy Seven Co. Ltd. Toky o 100-0064 (JP) Sasaki, Nortyvaki Chigasak-hi, Kanagawa 253-0021 (JP) National Institute of Maritime, Port and Avlation Technology on Union 	 Yamanaka Shipbuilding Co., Ltd. Ismabaci, Eskimo 754-0112 (JP) Kamorne Propeller Co., Ltd. Yokohama, Kanagawa 245-8542 (JP) [72] Imvention: SASAKI, Kortyuki Chigasaki-Sobel (JP) Kanagawa 253-9821 (JP) Kokya 100-0004 (JP) Ropresandulte Heid, Slephan Meisner Bolte Patentamälte Rechtamwälle Patrosrichalt mbB Wideemayestraße. 47 	
EP 3 103 715 A1	Tokyo 181-0004 (JP) (54) STEERING DEVICE, AND STEERING MET (56) [Object] To provide a stering device having its rudders not not deflected, which can provide a cult rudder system and a propeiler sighters an when the rudder system and a propeiler sighters and rudder of the site of th	action is divided into hao modes: the two-independent mode and the two-same direction modes, and each mode is dapted as dollows: at the time of dahead condition, each one of the two rudder pilate is retained on both sides of a propeiler parallel with a sign pink, and at the time of verinig of the two-same direction mode, a rudder pilate opposite to avering direction time 45 from aside of the propeiler to the downstream of the propeiler, and the other rudder pilate time 45 million aside of the propeiler to the downstream of the propeiler. And the propeiler to the downstream of the propeiler, and the propeiler to the downstream of the propeiler to a set of the upstream of the propeiler, and at the rud of the propeiler to the downstream of the propeiler to take a rudder arging of 00 m rome, to generate a thrust flow, and a method for steering the same to enhance a thrust flow by increase in a propeiler rate.	
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Fuel saving advantage of GRS



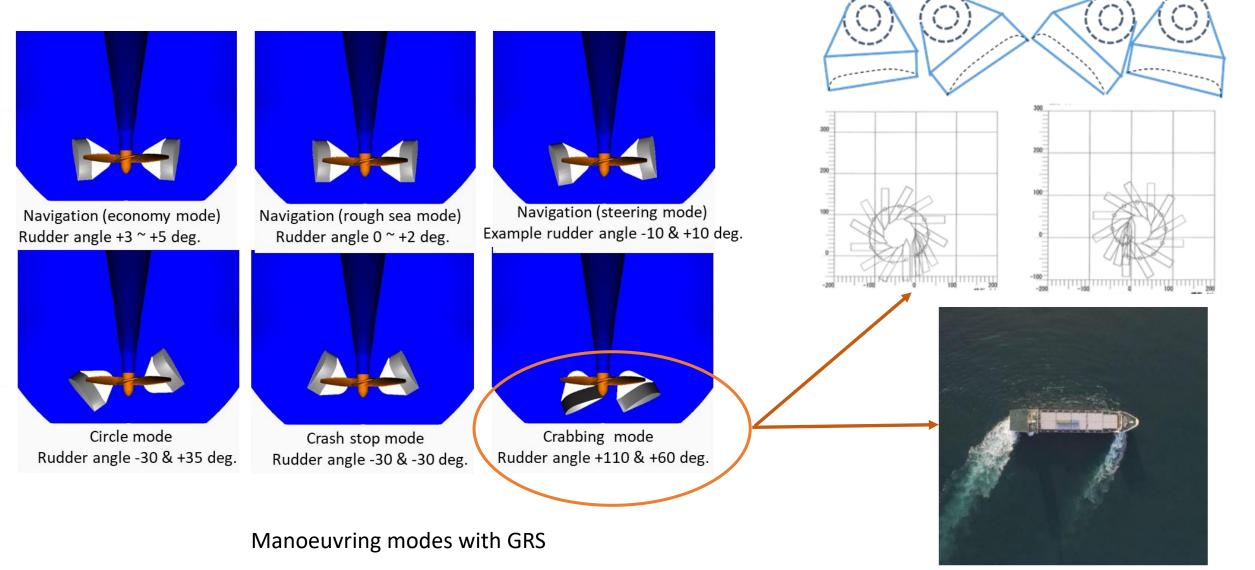


Trials (calm water) and in-service (including rough weather) powering performance comparisons of two sister ships: one with Gate rudder system, other with Conventional flap-rudder system In-service fuel consumption comparisons of two sister ships, Shigenobu with GRS (red) and Sakura with CRS (blue)



Manouverability advantage of GRS



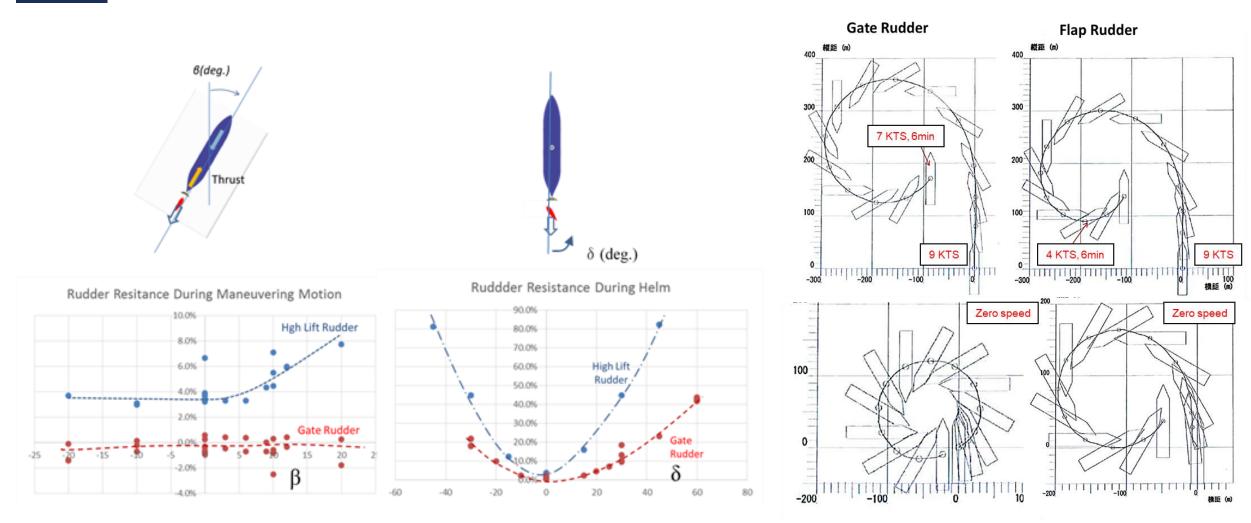


Crabbing mode



Manouverability advantage of GRS





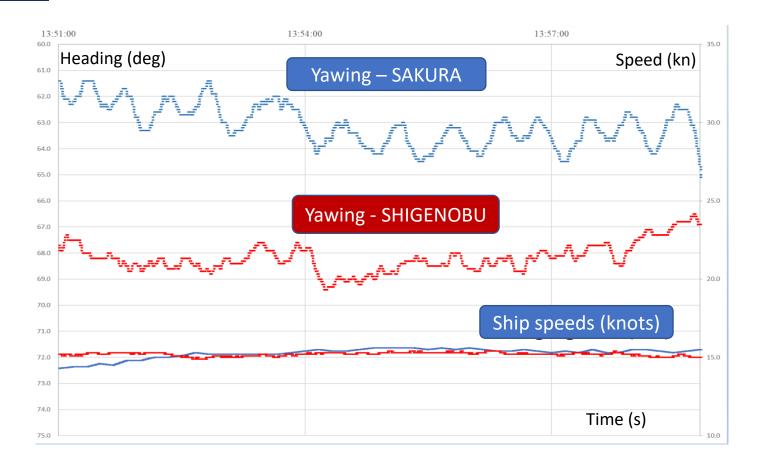
Comparison of rudder resistance (% Thrust) due to manoeuvring for conventional rudder and GRS.

Full-Scale 35^o Circle Test (Low Speed and Zero Speed) for Ship with conventional (flap) rudder and GRS



Seakeeping advantage of GRS





Comparison of time history yawing motions recorded in (almost) sideby-side trials with SAKURA (CR) and SHIGENOBU (GRS) containerships



Sea conditions: Wind speed: 12-24 knots Wave height: 1.5 – 2.0m Direction 250-270⁰ Period: 30 sec

Rolling motion recorded on inclinometer:

SAKURA \rightarrow 3-5° SHIGENBOU \rightarrow 1-3°



Motivations for GATERS Project

- The proposal responded to the H2020 Innovation Action call under the heading *"Retrofit Solutions and Next Generation Propulsion for Waterborne Transport"* (ID: LC-MG-1-8-2019).
- Although there was one new ship application of GRS ("Shigenobu"), there was/is no current application of the Gate Rudder System as a "retrofit" device, and hence it is proposed in GATERS for the first time and this, in fact, was the primary motivation of the GATERS proposal.
- GATERS, therefore, addressed the call text explicitly "to develop and demonstrate to TRL 6 and higher innovative, cost-effective retrofit solution for marine shipping which will provide substantial improvements regarding environmental impacts and life cycle cost".
- Recent IMO proposal for introducing the attained *Energy Efficiency Existing Ship Index (EEXI)* for ships of 400 GT and above













GATERS – Aims

- To bring together 18 technology experts and prime stakeholders, including the patent holder, to demonstrate and exploit the benefits of this system by two main deliverables:
- ➢ To demonstrate the GR system for the European short sea shipping operations by installing and operating on a target coastal vessel.
- ➤To explore the GR system, conceptually, for the oceangoing shipping operations, including fleet level.
- Hence to demonstrate if the Gate Rudder System can be the next generation propulsion and steering system for the waterborne transport.



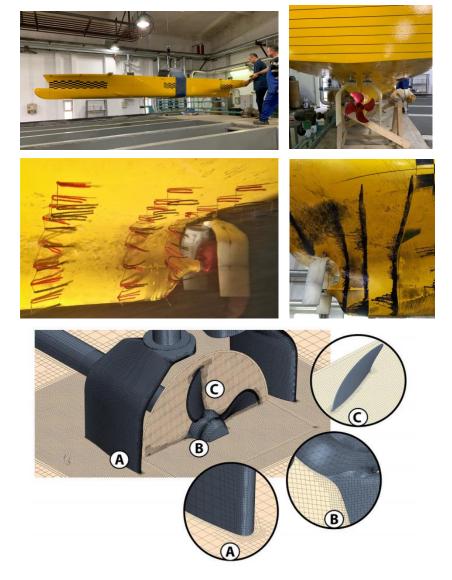




University of Strathclyde Glasgow

GATERS – Objectives

- 1. To investigate technical challenges of the Gate Rudder System (GRS) and to establish the best practice of application as a retrofit by using a combination of the computational, experimental and full-scale procedures.
- 2. To design a retrofit GRS at a detailed level, to manufacture and install on the coastal target cargo vessel. Hence, to demonstrate the effectiveness of the GRS by sea trials and voyage monitoring as well as its impact on the existing IMO regulations (i.e. EEDI, EEOI and Minimum power requirements) and the Life Cycle Cost (LCC).
- 3. To assess the overall impact of the retrofit GRS applications to major ship types for the European SSS operations and the Oceangoing Shipping (OS) operations on the existing (IMO) regulations and Life Cycle Cost (LCC) for both individual vessels as well as the fleet-level services.

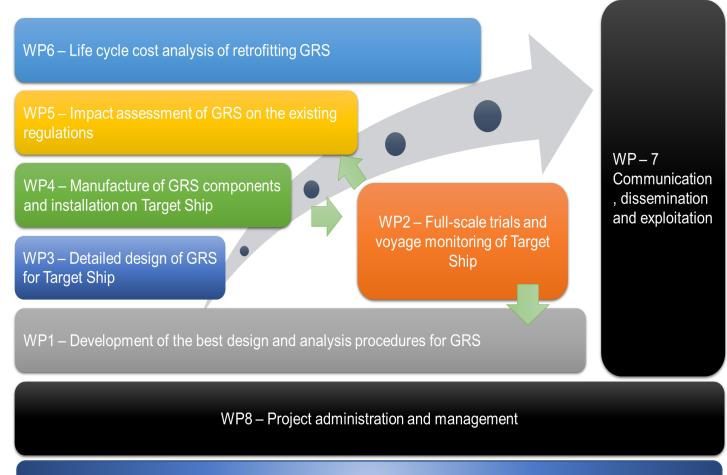




GATERS – Methodology



- Phase-1 (Feb'21 Feb'22): "Development of the best procedures for the design, manufacturing and retrofitting of the GRS" Critical design parts of the works to achieve the retrofitting of the GRS for the target cargo vessel will be completed.
- Phase-2 (Feb'22 Feb'23): "Detailed design, manufacturing and application of the GRS retrofitting on the target ship as well as its demonstration and further procedure development" – <u>Retrofitting on Sept'22</u>
- Phase-3 (Feb'23 Feb'24): "Impact of the GRS retrofitting on the existing and forthcoming regulations and life cycle cost for the European SSS operations and the Oceangoing Shipping operations" – An overall impact assessment of the GRS retrofitting for the major ship types at a fleet level will be conducted in this phase.



WP9 – Ethics requirements



GATERS – Partners



	Participant No.	Participant organisation name	Acronym	Country
University of Strathclyde Glasgow	1 (Coordinator)	UNIVERSITY OF STRATHCLYDE	UoS	UK
	2	HAMBURGISCHE SCHIFFBAU- VERSUCHSANSTALT GMBH	HSVA	DE
	3	BUREAU VERITAS MARINE & OFFSHORE REGISTRE INTERNATIONAL DE CLASSIFICATION DE NAVIRES ET DE PLATEFORMES OFFSHORE	BV	FR
VERITAS	4	GLAFCOS MARINE EPE	GME	EL
0 💦 🎽 →	5	CONSIGLIO NAZIONALE DELLE RICERCHE	CNR	IT
AND	6	HIDROTEKNIK YAT GEMI DENIZ YAPILARI TASARIM TEKNOLOJILERI SANAYI VE TICARET LIMITED SIRKETI	HYD	TR
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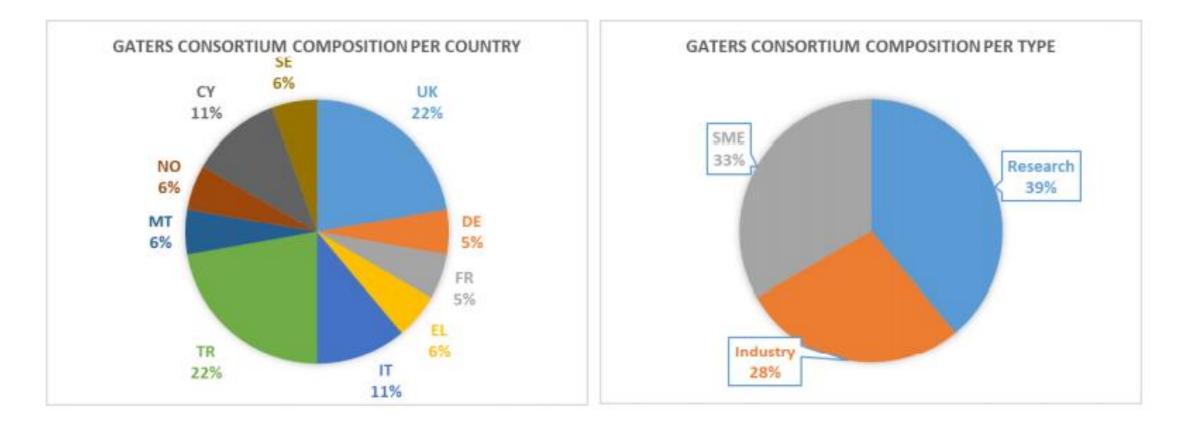


GATERS – Partners (continued)



TWI	Participant No.	Participant organisation name	Acronym	Country	
TWI	8	TWI LIMITED	TWI	UK	
	9	NAVAL ARCHITECTURAL SERVICES LIMITED	NAS	MT	-NAS
	10	CAPA DENIZCILIK NAKLIYAT SANAYI VETICARET LIMITED SIRKETI	CAPA	TR	NAVAL ARCHITECTURAL SERVICES
	11	SINTEF OCEAN AS	SINTEF	NO	
danans →	12	DANAOS SHIPPING COMPANY LIMITED	DANAOS	CY	
	13	STONE MARINE PROPULSION LIMITED	SMP	UK	
G G G ÜRDESAN ⇒	14	GURDESAN GEMI MAKINA SANAYI VE TICARET ANONIM SIRKETI	GURD	TR	PROPULSION
	15	UNIVERSITY OF NEWCASTLE UPON TYNE	UNEW	UK	← Newcastle University
STAR BULK →	16	STAR BULK SHIP MANAGEMENT CO. (CYPRUS) LTD	STARB	CY	×
	17	INFORMA UK LTD (LLOYD'S LIST INTELLIGENCE)	LLI	UK	← Intelligence
₽ CETENA⇒	18	CETENA S.P.A.	CETENA	IT	Moritime intelligence informa

GATERS – Partners background summary

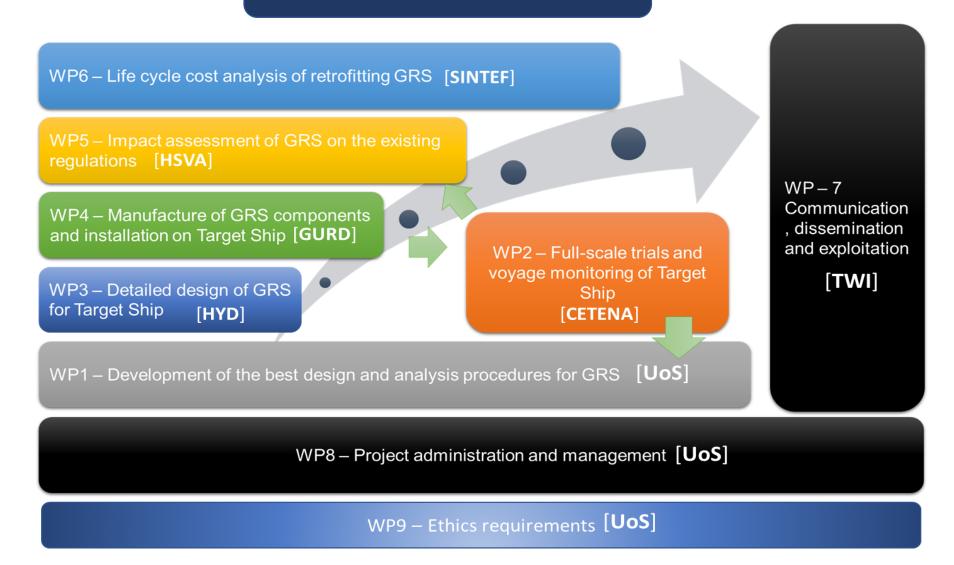


Distribution of GATERS Partners' background by Country (Left) & Type (Left)



GATERS – Work Packages

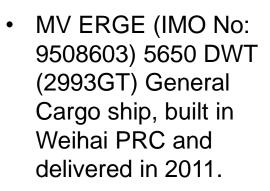




Schematic of GATERS Work Breakdown Structure in terms of Work Packages(WP) and associated leaders (WPL)



Target vessel – MV ERGE To be retrofitted with GRS



- She operates in European Coastal waters, Black Sea, Red Sea and North African waters
- She is owned by partner CAPA and she has sister vessel MV ERLE with conventional flap rudder

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Parameter			MV Erge								
	Symbol	Units	Ballast Load	Design Load	Full Load						
Length overall	L _{OA}	(m)		89.95							
Length between perpendiculars	L _{BP}	(m)		84.95							
Breadth	В	(m)		15.4							
Draught (midship)	Т	(m)	3.3	5.6	6.45						
Draught (AP)	Τ _Α	(m)	3.8	5.6	6.45						
Draught (FP)	T _F	(m)	2.8	5.6	6.45						
Displacement	Δ	(ton)	3607	6339	7241						
Block coefficient	C _B		0.818	0.827	0.84						
Prismatic coefficient	C _P		0.823	0.843							
Midship area coefficient	C _M		0.994								
Waterplane area coefficient	C _{WP}		0.854	0.916	0.944						
Longitudinal centre of buoyancy	LCB	(m) (+ fwd)	46.866	45.85	43.025						
Longitudinal centre of floatation	LCF	(m) (+ fwd)	46.246	39.748	39.863						
Longitudinal centre of gravity	LCG	(m) (+ fwd)	46.903 45.91 43.03								
Verticle centre of gravity	VCG	(m)	3.23	5.4	6.095						
Speed	Vs	knots		12							













GATERS – Implementation



WP1 - DEVELOPMENT OF THE BEST DESIGN & ANALYSIS PROCEDURES FOR GRS

GATE RUDDER SYSTEM AS A RETROFIT FOR THE NEXT GENERATION PROPULSION AND STEERING OF SHIPS (GATERS)				Phase	0						Phase	-2							Phas	e-3			Ç
	M1 M2	M3 M	4 M5			M10	M11 M12	M13 N	114 M15	M16 M17			M21	M22 N	123 M24	M25 N	126 M2	7 M28 M2			2 M33 N	134 M3	5 M36
WP 1 DEVELOPMENT OF THE BEST DESIGN AND ANALYSIS PROCEDURES FOR THE GRS																							
T 1.1 Investigation and data collection of the existing vessels with the GRS and selection of other vessel types																						-	+
T 1.1.1 Collection of the relevant data of the existing vessel with the GRS		•																					
T 1.1.2 Collection of the relevant technical and operational data for the target vessel																							
T 1.1.3 Selection and data collection of representative vessel types for EU SSS and OS operations																							
T1.2 Initial design tool development for GRS																							
T 1.2.1 Establish simple algorithm to estimate the main particulars of the basic GRS components			\Rightarrow																				
T 1.2.2 Determination of the preliminary dimensions of the GRS for the target ship																							
T 1.2.3 Further enhance the accuracy of the initial design tool iteratively															\Rightarrow								
T 1.3 Development/implementation of accurate model test procedures for ship models with GRS																							
T1.3.1 R&P, seakeeping, noise and cavitation tests with an existing 5m container model at ITU facilities								•															
T1.3.2 Manoeuvring tests with the free sailing container model in the ITU campus lake								•															
T1.3.3 Manufacture of a 12m container model and R&P tests in the HSVA towing tank					\Rightarrow																		
T1.3.4 R&P, seakeeping, noise and cavitation tests with a 6m target ship model at the CRN-INM facilities							\Rightarrow	•															
T1.3.5 Manoeuvring tests with the free sailing tanker model in the CNR-INM lake facilities							\downarrow	•															
T1.3.6 Detailed flow investigation around GRS system using laser-based devices in ECT							\Rightarrow	•															
T1.3.7 Dedicated performance and load measurements of GRS in open waters and waves in KHL							\Rightarrow																
T 1.4 Development of accurate CFD procedures for the full-scale performance prediction of a ship with GRS																							
T1.4.1 Calm water powering performance prediction in the model and full scale for the container vessel with GRS																							
T1.4.2 Calm water powering performance prediction in the model and full scale for the target vessel with GRS															\Rightarrow								
T 1.5 Development of accurate Manoeuvring and Seakeeping simulation tools for a ship with GRS																							
T 1.5.1 Manoeuvring in calm water and seakeeping in waves for the model and full-scale container vessel															\Rightarrow								
T 1.5.2 Manoeuvring in calm water and seakeeping in waves for the model and full-scale target vessel															\Rightarrow								
T 1.6 Development of accurate structural design and analysis procedures for GRS																							
T 1.6.1 Full-scale structural analysis of the GRS for the container vessel																							
T 1.6.2 Full-scale structural analysis of the GRS for the target vessel																							
T 1.7 Structural design and weight optimisation of the GRS using new materials																							
T 1.7.1 Investigation of potential new materials for GRS (GFRP/CFRB) and lab based material testing															\Rightarrow								
T 1.7.2 Implementation and demonstration of the weight optimised GRS															\Rightarrow								





WP 3 – DETAILED DESIGN OF GRS FOR TARGET SHIP

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| Work packages & Tasks | M1 N | t2 N | 13 M4 | 4 M5 | 5 M6 | M7 N | M8 M

 | 19 M3 | 0 M11

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 | 114 M15

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 | M17 M | 18 M19

 | 9 M20 | M21 M
 | 22 M2

 | 3 M24 | M25 | M26 N | M27 M2 | 28 M2 | 9 M30 I
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 | M34 M | 135 M3 | 4
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| Full-scale trials and voyage monitoring of target ship | | | | | | |

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| Onboard data measurements with the target ship by sea trials and voyage monitoring in-service | | | | | | |

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| Strategic planning to conduct the onboard and off-board measurement activities | | ♦ | | | | |

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| Fitting of a voyage performance monitoring system to the target ship | | 5 | | ļ | \geq | |

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| Conduct of voyage performance monitoring in-service before the GRS retrofitting | | | | | | |

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| Drydock the vessel and clean the hull | | | | | | |

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| Conduct of dedicated sea trials just before the GRS retrofitting | | | | | | |

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| Conduct of dedicated sea trials just after the GRS retrofitting | | | | | | |

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| Conduct of voyage performance monitoring in-service after the GRS retrofitting | | | | | | |

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| Off-board data (URN) measurements with the target ship by sea trials | | | | | | |

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| Conduct of the URN measurements with the target ship before the retrofit | | | | | | |

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| Conduct of the URN measurements with the target ship after the retrofit | | | | | | |

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| DETAILED DESIGN OF THE GRS FOR THE TARGET (TANKER) SHIP | | | | | | |

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| Design of GRS for the target ship and class approval | | | | | | |

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| Conduct the detailed hydrodynamic design of the GRS | | | | | | |

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| Conduct the detailed structural design and optimisation of the GRS | | | | | | |

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| Produce manufacture drawings and secure class approval | | | | | | |

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| Detailed design of new propeller blades | | | | | | |

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| Conduct of the detailed structural design of the propeller to fit in the existing shaft | | | | | | |

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| Conduct of manufacturing drawings and securing of class approval | | | | | | |

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| Specification and purchase of the steering gear machinery and control systems | | | | | | |

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| Specification of the steering gear requirements and supplier selection | | | | | | |

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| Overall detailed design integration of the GRS | | | | | | |

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| Review the SG room and explore the possible alteration options | | | | | | |

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| Integration of all the GRS components and evaluation of its impact on the existing steering gear room | | | | | | |

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| Conduct hydrostatic analysis for the retrofited target vessel and class approval | | | | | | |

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| | Full-scale trials and voyage monitoring of target ship Onboard data measurements with the target ship by sea trials and voyage monitoring in-service Strategic planning to conduct the onboard and off-board measurement activities Fitting of a voyage performance monitoring system to the target ship Conduct of voyage performance monitoring in-service before the GRS retrofitting Drydock the vessel and clean the hull Conduct of dedicated sea trials just before the GRS retrofitting Conduct of dedicated sea trials just after the GRS retrofitting Conduct of dedicated sea trials just after the GRS retrofitting Conduct of voyage performance monitoring in-service after the GRS retrofitting Onfboard data (URN) measurements with the target ship by sea trials Conduct of the URN measurements with the target ship before the retrofit Conduct of the URN measurements with the target ship after the retrofit DestalLED DESIGN OF THE GRS FOR THE TARGET (TANKER) SHIP Design of GRS for the target ship and 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WP 4 – MANUFACTURING OF GRS COMPONENTS & INSTALLATION ON TARGET SHIP



WP 5 – IMPACT ASSESSMENT OF GRS ON EXISTING & FORTHCOMING REGULATIONS

WP 6 – LIFE CYCLE COST ANALYSIS OF RETROFITTING GRS

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GATE R	JDDER SYSTEM AS A RETROFIT FOR THE NEXT GENERATION PROPULSION AND STEERING OF SHIPS (GATERS)					Pha	se-1								Phase-2								Pha	se-3				
	Work packages & Tasks	M1	M2 M3	S M	4 MS	M6	M7	M8 P	M9 M3	0 M11	M12	M13	M14 M15 M3	6 M17	M18 M11	9 M20 M	21 M23	2 M23 M2	4 M25	M26	M27 P	428 M21	M30	M31	M32 I	M33 M	(34 MP	5 M36
		_			-	-						_														-	Ŧ	
	MANUFACTURING OF THE GRS COMPONENTS AND INSTALLATION ON THE TARGET SHIP			+	\rightarrow	-				-		_									$ \downarrow \downarrow$						\rightarrow	<u>+</u> _'
	Strategic planning of the GRS installation on the target ship			\perp	\rightarrow							_					_				$ \downarrow \downarrow$						\rightarrow	<u>+_'</u>
	Review of the target ship's original steering gear room and machinery			\perp								_		>														<u>+_'</u>
	Review of the GRS components and their installation requirements in the steering gear room											_		>														<u> </u>
T 4.1.3	Making plan (i.e. procedure steps) for the installation process											_		>														<u> </u>
	Manufacture and purchase of the GRS components																											<u> </u>
<u> </u>	Manufacturing of the gate rudder blades and delivery to the ship yard									\perp				\Rightarrow		\perp											\perp	<u> </u>
T 4.2.2	Manufacturing of the new propeller blades and delivery to the ship yard													\Rightarrow														<u> </u>
T 4.2.3	Purchasing of the steering gear machinery and autopilot and delivery to the shipyard													\Rightarrow	·													'
T 4.3	Installation of the GRS on the target ship																											
T 4.3.1	Removal of the existing Steering Gear (SG) system and enhancement of the SG room													≙														
T 4.3.2	Installation of the GR system components as required and planned														₩>													
WP 5	IMPACT ASSESSMENT OF THE GRS ON THE EXISTING AND FORTHCOMING REGULATIONS																											
T 5.1	Impact on the IMO requirements and EU regulations for the target vessel																											'
T 5.1.1	To assess the impact on the target ship in terms of the IMO's requirements											=				+		++	>									'
T 5.1.2	To assess the impact on the target ship in terms of the EU regulations										L F	\rightarrow		_			_	\Rightarrow	>									'
T 5.2	Impact on the IMO requirements and EU regulations for wider ship types and different operations																											'
T 5.2.1	To assess the impact on the representative wider ship types for the EU SSS operations																								\Rightarrow			'
T 5.2.2	To assess the impact on the representative wider ship types for the OS operations																								\Rightarrow			'
T 5.3	Impact on the IMO requirements and EU regulations for wider ship types at fleet level operations																											
T 5.3.1	To assess the impact on the representative wider ship types for the EU SSS fleets																											>
T 5.3.2	To assess the impact on the representative wider ship types for the OS fleets																											>
WP 6	LIFE CYCLE COST (LCC) ANALYSIS OF RETROFITTING A GRS																											
T 6.1	Cost effectiveness analysis and comparison amongst GRS solutions and against other ESDs																											
T 6.1.1	Development of CAPEX and OPEX for different types and sizes of vessels equipped with GRS																\geq											
T 6.1.2	Comparative CAPEX and OPEX analysis of GRS for new build and retrofited ships																											
T 6.1.3	Comparative CAPEX and OPEX analysis of GRS against other selected energy-saving devices																\geq											
T 6.2	LCC analysis for the GRS retrofit																											
T 6.2.1	LCC analysis of retrofitting the GRS for the target ship																		>									
T 6.2.2	LCC analysis of retrofitting the GRS for the wider ship types for the EU SSS and OS			Τ																					\Rightarrow			
T 6.2.3	LCC analysis of retrofitting GRS to the fleets																									_	÷	>
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WP8 – PROJECT ADMINISTRATION & MANAGEMENT

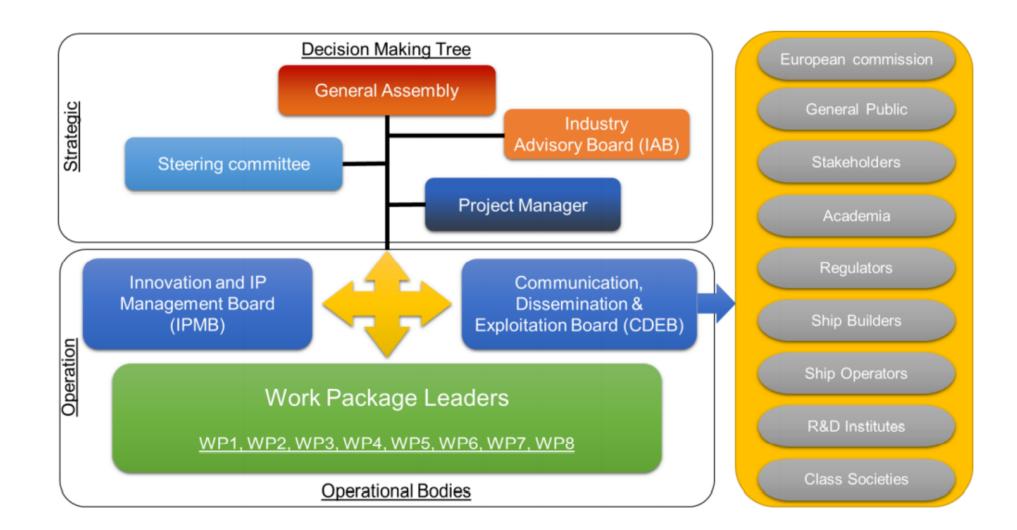
WP9 – ETHICS REQUIREMENTS

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GA	E RUDDER SYSTEM AS A RETROFIT FOR THE NEXT GENERATION PROPULSION AND STEERING OF SHIPS (GATERS)					Ph	1250									Phase 1	2								Pha	ise-3				
	Work packages & Tasks	M1	M2	M3	M4 N	15 M6	M7	M8	M3 N	410 M3	11 M12	M13 P	414 M1	5 M16	M17 N	M18 M1	9 M20	M21 N	422 M	23 M24	M25	M26	M27	M28 M2	9 M30	M31 M	132 M	33 M34	M35 /	M36
WP	7 COMMUNICATION, DISSEMINATION AND EXPLOITATION ACTIVITIES																													
Т7.	Strategic planning, coordination and organisation																													
Т7.	Project communication activities																													
Т7.	8 Project dissemination activities																													
Т7.	8 Project exploitation activities																													
WP	8 PROJECT ADMINISTRATION AND MANAGEMENT																													
Т8.	Administrative and financial management																													
Т8.	2 Scientific and technological management																													
MS	PROJECT MILESTONES										MS1	N	1S2		Ν	VIS3	MS4									N	155		1	VIS6
GA	E RUDDER SYSTEM AS A RETROFIT FOR THE NEXT GENERATION PROPULSION AND STEERING OF SHIPS (GATERS)	M1	M2	M3	M4 N	15 M6	M7	M8	M9 N	/10 M1	1 M12	M13 N	114 M15	5 M16 I	M17 N	M18 M19	9 M20	M21 N	122 M	23 M24	M25	M26	M27	M28 M2) M30	M31 M	32 M	33 M34	M35	/36



GATERS – Management structure









GATERS – Management, Communication, Dissemination & Exploitation Activities Support Boards

GATERS - Innovation and IP Management Board (IPMB)

Project Members	GME	HYD	SMP	TWI	UoS
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GATERS - Communication, Dissemination and Exploitation Board (CDEB)

Project Members	САРА	GME	HYD	SMP	TWI	UNEW	UoS
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GATERS - Industry Advisory Board (IAB) and representatives

Member Institution / Company	Royal Caribbean Cruise Ltd	Wartsila Netherlands BV	Hellenic Tankers Co Ltd	Oscar Propulsion Ltd	Kuribayashi Steam Co Ltd	Shell Int'l Trad & Shipping Co Ltd
Member's	Dr Tor E	Dr Elias	Dr Christos	Mr David	Mr Hirohisa	Mr James
Representative	Svensen	Boletis	Vervenitos	Taylor	Inada	Cocks



GATERS – Financial



	Project fund		
Total Project Fund [EUR]	EU Contribution [EUR]	Industry Contribution [EUR]	
5,878,364.25	4,999,509.98	878,854.27	

Project cost breakdown

Personal cost [EUR]	Travel, Equipment & Other cost [EUR]	Indirect cost (25% Flat rate) [EUR]	Total cost [EUR]
3,131,085.40	1,571,606.00	1,175,672.85	5,878,364.25

Project time and effort					
Project elapsed duration [months]	Project person efforts [months]				
36	694				





- Project was officially started in February 2021 with a kick-off meeting held on 24th of February
- Project website was launched as well as other CDE activities have been underway including social media interfaces
- WP1 (Preliminary Gate Rudder Design; Model testing and CFD modelling procedure development tasks); WP2 (Target Vessel Trials and Monitoring System installation and data collection task); WP7 (Communication, Dissemination and Exploitation activities tasks); WP8 (Day-to-day management tasks) are underway
- First two critical milestones (MS1 and MS2) are to complete the model tests and confirm the design of the GRS for MV ERGE on M12 and 14, respectively.

www.gatersproject.com

Object		Publications	News and Events	Consortium	Cor
Sarch S	I aretrofit Gate Rudder System (GRS) and demonst monitoring. The retrofit Gate Rudder System (GR insone The GATES consortium consist of 16 party stary to Geneticy desimination and equipt the prop Programme (Dr. 950337) with the independent an an Virgital Netherlands DV to utilise the Gate Rudder	Home Explore () () () () () () () () () () () () ()	Description The aim of the GATERS project is to design, m and demonstrate the effectiveness of the retor retord solution for GRS will directly improve th emission. The GATERS consortium consists of complementary expertise necessary to develop GATERS innovation Action Project is sponsore independent aim and objectives.	AANNELS DISCUSSION ABOUT nufacture and install a retrofit Gate Rudder System (GR fit GR5 through sea trials and vyoge monitoring The e vessels performance in energy efficiency and CO2 15 partnes aroze stronger, All the partners have a disseminate and exploit the project. d by the EC H0202 Programme (ID: 660337) with the as an official sub-license agreement with Vartsila it (EP 3103715) at specific retrofit projects of vessel	Q.
Given Service Gogerssproject The aim of the GATERS project is to design, manuf Rudder System (GRS) and demonstrate the effective Dianed March 2021 O Following 2 Followers		faceboo		TER	1 Message



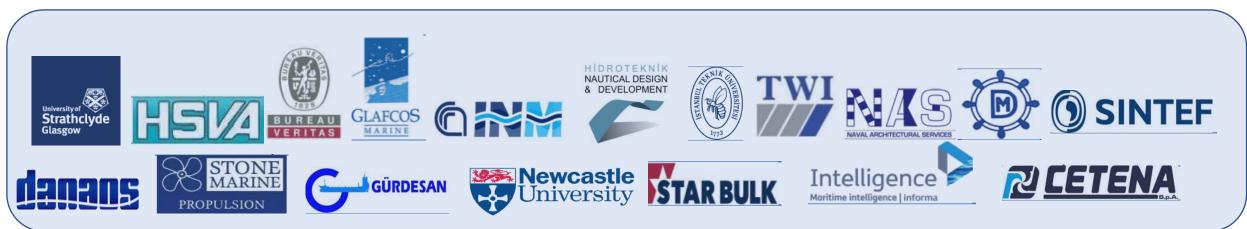




THANK YOU

mehmet.atlar@strath.ac.uk
www.strath.ac.uk/naome/

on behalf of the GATERS Consortium





GATERS Project - Summary



- Project number: 860337
- **Project Acronym**: GATERS
- Project title: GATE Rudder System as a Retrofit for the Next Generation Propulsion and Steering of Ships
- Call (part) ID: H2020-MG-2019-Two-Stages
- Topic: LC-MG-1-8-2019 (Retrofit Solutions and Next Generation Propulsion for Waterborne Transport)
- Fixed EC Keywords: Maritime, Low emission technology in transport
- Free keywords: Novel propulsion and manoeuvring system; Retrofit technology; Short sea shipping
 operations; Oceangoing shipping operations; Generic and flexible propulsion system; IMO requirements for
 Emission
- Starting Date: 1 February 2021
- Duration: 36M
- Funding: 5.894,822.5 M EUR (total); 4,999,510.0M ER (EU requested)
- Call (part) ID: H2020-MG-2019-TwoStages
- Partners no: 18 (11 Industry + 4 Research Institutes + 3 Universities)
- Country no: 9
- Partners : UoS(UK); HSVA(DE); BV(FR); GME(GR); CNR(I); HYD(TR); ITU (TR); TWI (UK); NAS (MT); CAPA(TR); SINTEF(NO); DANAOS(CYP); SMP(UK); GURD(TR); UNEW(UK); STARB(CYP); LLI(UK); CETENA(I)
- Coordinator: University of Strathclyde (UoS) ; Prof Mehmet Atlar (<u>mehmet.atlar@strath.ac.uk</u>) ; Tel: +447900890228